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(54) **SURGICAL FORCEPS FOR SEALING AND DIVIDING TISSUE**

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CPC **A61B 18/1445** (2013.01); **A61B 2018/0063** (2013.01); **A61B 2018/00601** (2013.01); **A61B 2018/1452** (2013.01); **A61B 2018/1455** (2013.01)

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See application file for complete search history.

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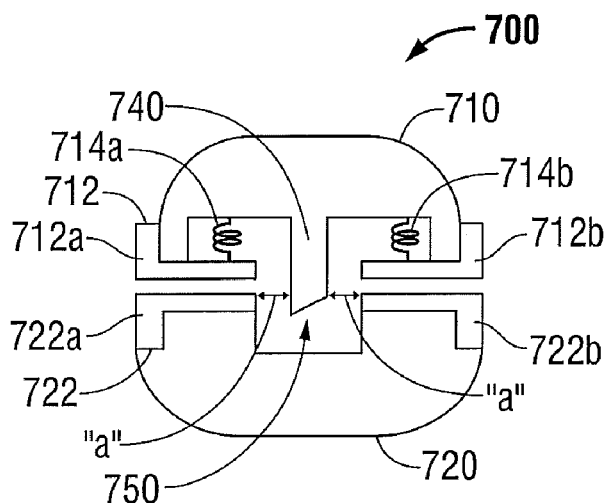
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(57) **ABSTRACT**

A forceps includes an end effector assembly including a pair of jaw members disposed in opposing relation relative to one another. At least one jaw member is moveable relative to the other between a spaced apart position, a first approximated position, and a second approximated position. The jaw members are configured to apply a pre-determined pressure to tissue disposed therebetween in each of the first and second approximated positions. A sealing pressure is applied to tissue disposed between the jaw members when the jaw members are in the first approximated position. A cutting pressure is applied to tissue disposed between the jaw members when the jaw members are in the second approximated position.

18 Claims, 5 Drawing Sheets



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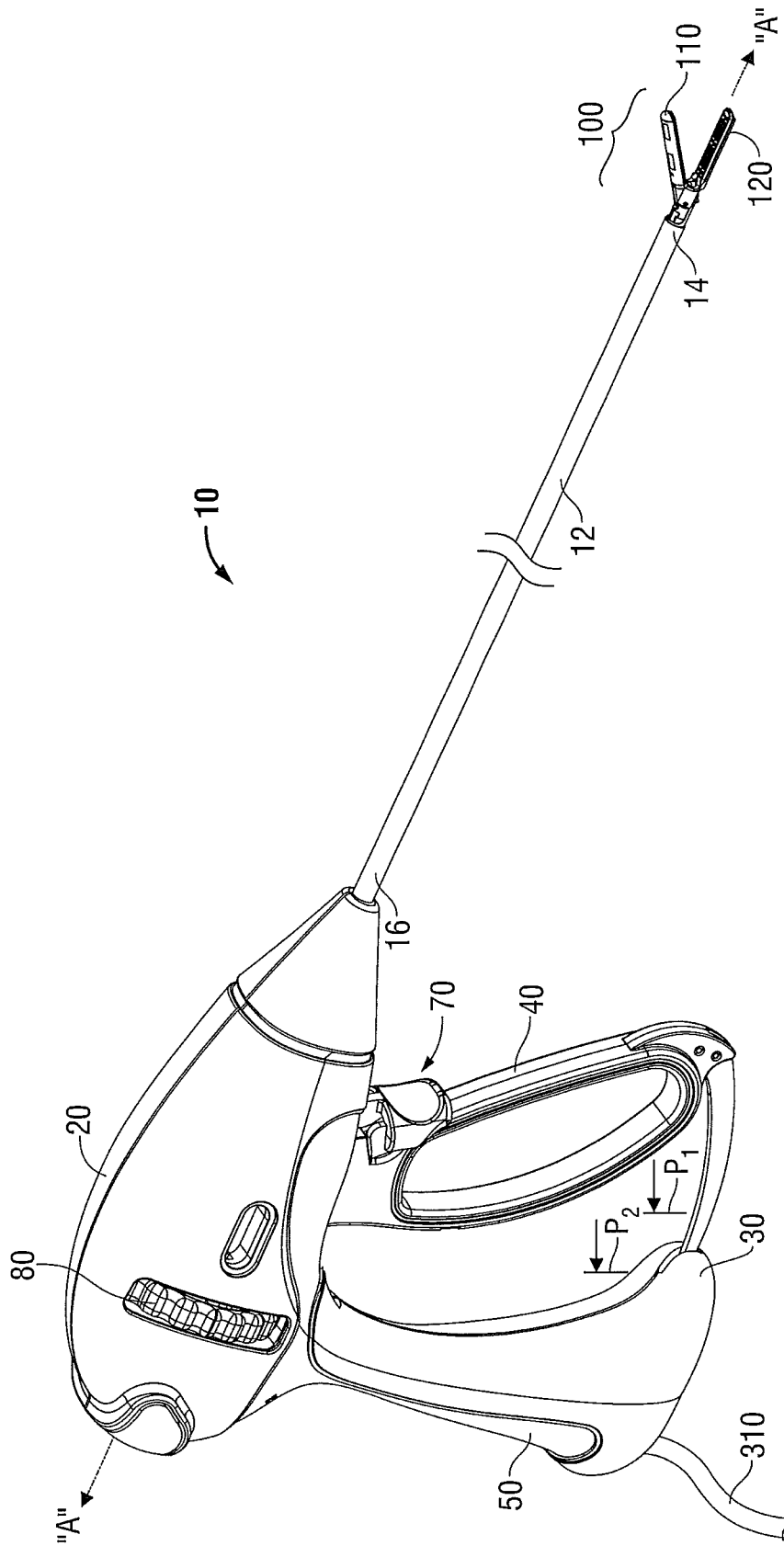


FIG. 1

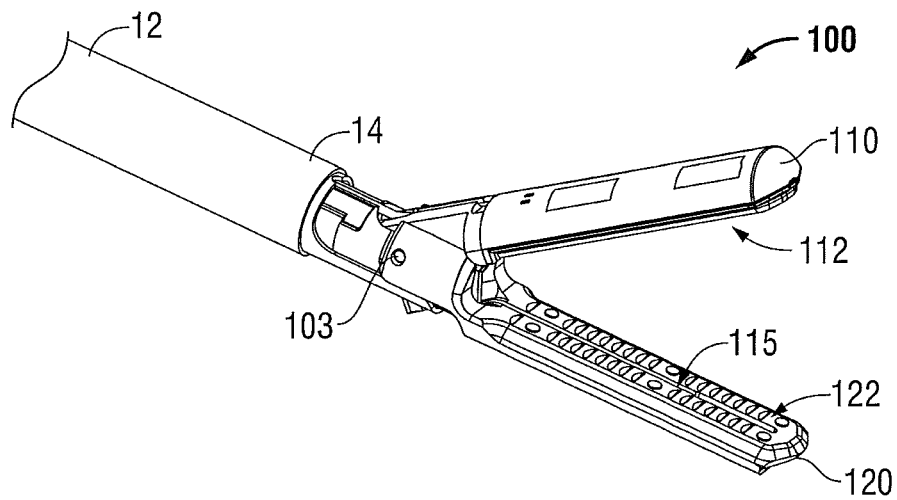


FIG. 2

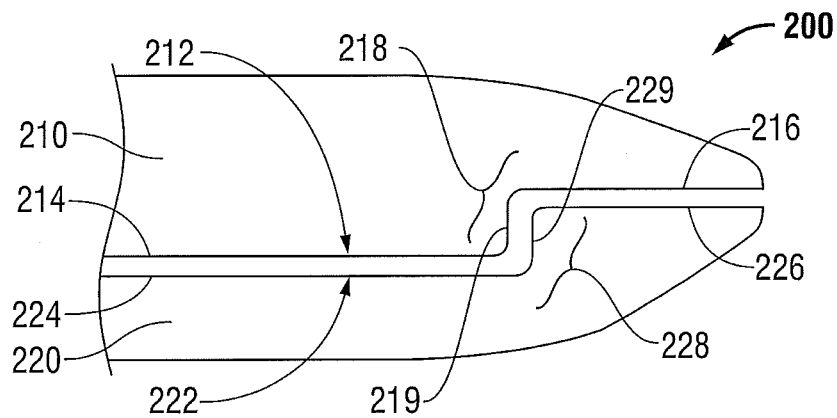


FIG. 3

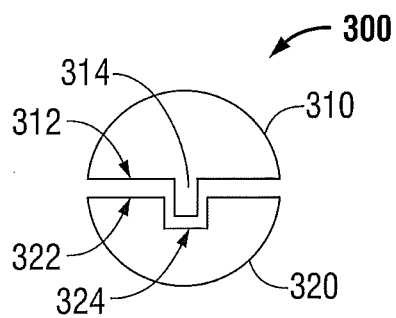


FIG. 4

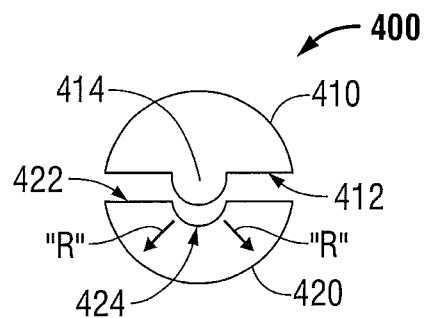


FIG. 5

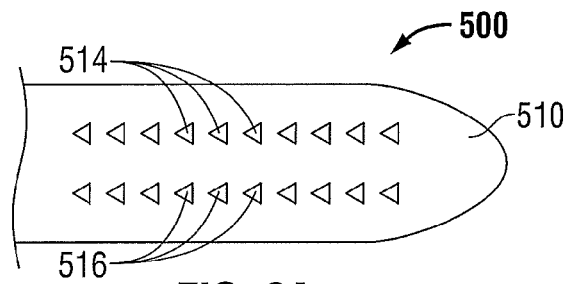


FIG. 6A

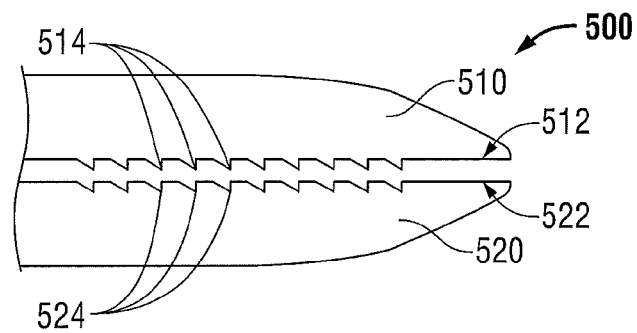


FIG. 6B

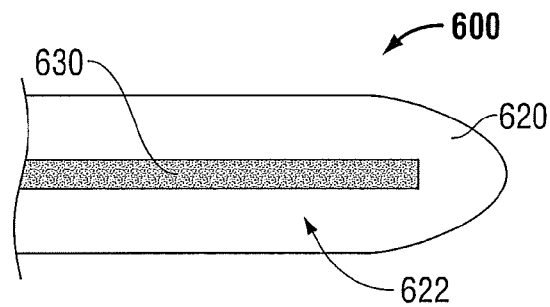


FIG. 7A

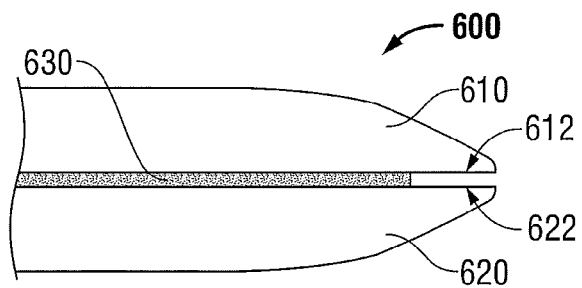


FIG. 7B

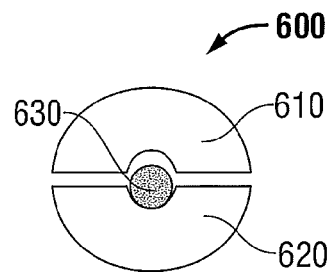


FIG. 7C

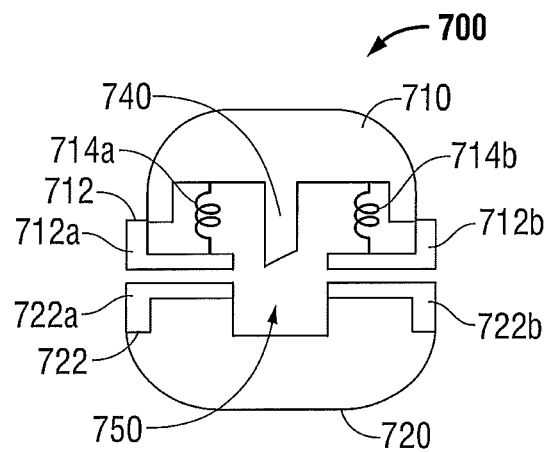


FIG. 8A

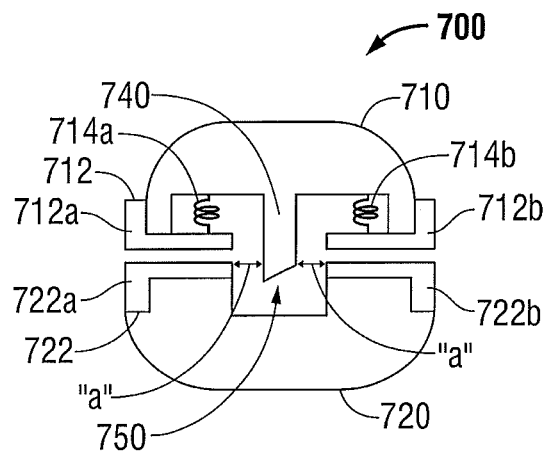


FIG. 8B

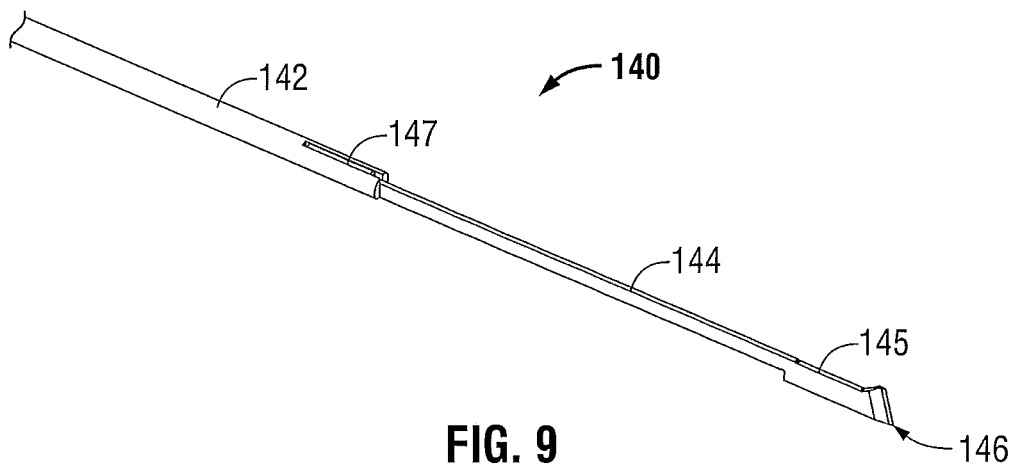


FIG. 9

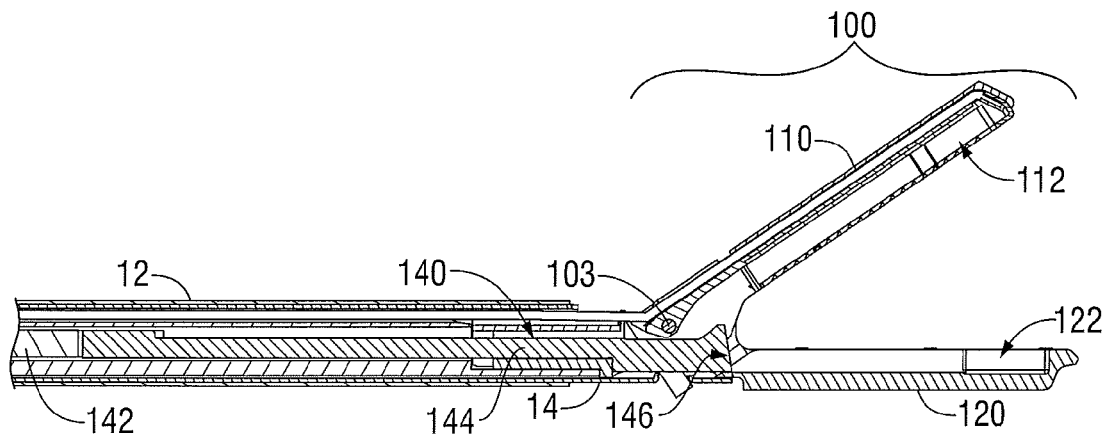


FIG. 10

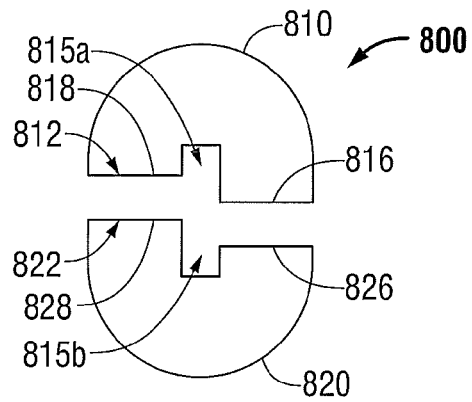


FIG. 11

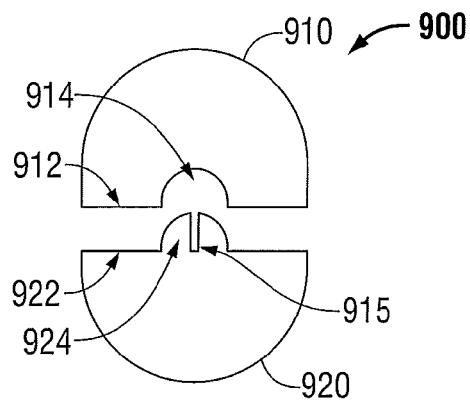


FIG. 12

1

SURGICAL FORCEPS FOR SEALING AND DIVIDING TISSUE

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a divisional application of U.S. patent application Ser. No. 12/821,253, filed on Jun. 23, 2010, now U.S. Pat. No. 8,647,343, the entire contents of which are hereby incorporated herein by reference.

BACKGROUND

The present disclosure relates to surgical instruments. More particularly, the present disclosure relates to surgical forceps for sealing and/or cutting tissue.

TECHNICAL FIELD

Electrosurgical forceps utilize both mechanical clamping action and electrical energy to effect hemostasis by heating tissue and blood vessels to coagulate, cauterize and/or seal tissue. As an alternative to open forceps for use with open surgical procedures, many modern surgeons use endoscopic or laparoscopic instruments for remotely accessing organs through smaller, puncture-like incisions or natural orifices. As a direct result thereof, patients tend to benefit from less scarring and reduced healing time.

Endoscopic instruments, for example, are inserted into the patient through a cannula, or port, which has been made with a trocar. Typical sizes for cannulas range from three millimeters to twelve millimeters. Smaller cannulas are usually preferred, which, as can be appreciated, ultimately presents a design challenge to instrument manufacturers who must find ways to make endoscopic instruments that fit through the smaller cannulas.

Many endoscopic surgical procedures require cutting or ligating blood vessels or vascular tissue. Due to the inherent spatial considerations of the surgical cavity, surgeons often have difficulty suturing vessels or performing other traditional methods of controlling bleeding, e.g., clamping and/or tying-off transected blood vessels. By utilizing an endoscopic electrosurgical forceps, a surgeon can either cauterize, coagulate/desiccate and/or simply reduce or slow bleeding simply by controlling the intensity, frequency and duration of the electrosurgical energy applied through the jaw members to the tissue. Most small blood vessels, i.e., in the range below two millimeters in diameter, can often be closed using standard electrosurgical instruments and techniques. However, if a larger vessel is ligated, it may be necessary for the surgeon to convert the endoscopic procedure into an open-surgical procedure and thereby abandon the benefits of endoscopic surgery. Alternatively, the surgeon can seal the larger vessel or tissue. Typically, after a vessel or tissue is sealed, the surgeon advances a knife to sever the sealed tissue disposed between the opposing jaw members.

SUMMARY

The present disclosure relates to a surgical forceps including an end effector assembly. The end effector assembly includes a pair of jaw members disposed in opposing relation relative to one another. One or both jaw members are moveable relative to the other between a spaced-apart position, a first approximated position and a second approximated position. The jaw members are configured to apply a pre-determined pressure to tissue disposed between the jaw members

2

in the first and second approximated positions. More specifically, a sealing pressure is applied to tissue disposed between the jaw members when the jaw members are in the first approximated position. When the jaw members are in the second approximated position, a cutting pressure is applied to tissue disposed therebetween.

In one embodiment, one or both of the jaw members are adapted to connect to an electrosurgical energy source to communicate energy to tissue disposed between the jaw members to seal tissue disposed therebetween when the jaw members are in the first approximated position.

In another embodiment, a knife assembly and a knife channel defined within one or both of the jaw members are provided. The knife assembly includes a knife blade that, upon activation, is configured to translate distally to extend into the knife channel(s) to cut tissue disposed between the jaw members.

In still another embodiment, an opposing surface of each jaw member defines a complementary stepped portion. When the jaw members are moved to the second approximated position, tissue disposed between the jaw members is cut by the engagement of the complementary stepped portions. The complementary stepped portions may be defined longitudinally along the jaw members such that a distal end of each jaw member is offset from a proximal end of each jaw member or, alternatively, the complementary stepped portions may be defined laterally across the jaw members such that a first side of each jaw member is offset from a second side of each jaw member.

In yet another embodiment, one of the jaw members includes a protrusion, or flange extending longitudinally along an opposed surface thereof and the other jaw member includes a complementary recess similarly extending longitudinally along an opposed surface thereof. When the jaw members are moved to the second approximated position, the flange engages the recess to cut tissue disposed between the jaw members.

In still yet another embodiment, one of the jaw members includes a plurality of protrusions disposed along an opposed surface thereof and the other jaw member includes a plurality of complementary recesses extending longitudinally along an opposed surface thereof. Each recess is configured to engage one of the protrusions to cut tissue disposed therebetween when the jaw members are moved to the second approximated position.

In another embodiment, one or both of the jaw members includes a ceramic bar disposed thereon and extending longitudinally therealong. The ceramic bar is configured to cut tissue disposed between the jaw members upon movement of the jaw members to the second approximated position.

In still yet another embodiment, a fixed blade positioned within one of the jaw members. The jaw member also includes an opposed surface moveably coupled thereto. More specifically, the opposed surface is moveable with respect to the jaw member between a spaced position and a closer position. Upon movement of the jaw members to the second approximated position, the opposed surface is moved to the closer position with respect to the jaw member such that the fixed blade is urged through tissue disposed between the jaw members to cut tissue disposed therebetween. The opposed surface may be coupled to the jaw member by a spring mechanism. Further, the spring mechanism may be configured to bias the opposed surface toward the spaced position.

A method of sealing and dividing tissue is also provided in accordance with the present disclosure. The method includes providing a forceps according to any of the embodiments discussed above. The jaw members are moved to the spaced

3

apart position and the forceps is positioned such that tissue is disposed between the jaw members. The jaw members are then moved from the spaced-apart position to the first approximated position where the sealing pressure is applied to seal tissue disposed between the jaw members. Next, the jaw members are moved to the second approximated position where the cutting pressure is applied to cut tissue disposed between the jaw members.

In one embodiment, in order to seal tissue disposed between the jaw members, electrosurgical energy is applied to the jaw member(s) when the jaw members are in the first approximated position.

In another embodiment, when the jaw members are in the second approximated position, a knife blade is translated distally to extend through knife channel(s) defined within the jaw members to cut tissue disposed between the jaw members.

BRIEF DESCRIPTION OF THE DRAWINGS

Various embodiments of the presently disclosed forceps are described herein with reference to the drawings, wherein:

FIG. 1 is a perspective view of a forceps having an end effector assembly in accordance with an embodiment of the present disclosure;

FIG. 2 is an enlarged, perspective view of the end effector assembly of the forceps of FIG. 1;

FIG. 3 is a side, cross-sectional view of one embodiment of jaw members for use with the end effector assembly of FIG. 1;

FIG. 4 is a front, cross-sectional view of another embodiment of jaw members for use with the end effector assembly of FIG. 1;

FIG. 5 is a front, cross-sectional view of yet another embodiment of jaw members for use with the end effector assembly of FIG. 1;

FIG. 6A is a top view of a still another embodiment of a jaw member for use with the end effector assembly of FIG. 1;

FIG. 6B is a side, cross-sectional view of the jaw member of FIG. 6A and a corresponding jaw member for use with the end effector assembly of FIG. 1;

FIG. 7A is a top view of still yet another embodiment of a jaw member for use with the end effector assembly of FIG. 1;

FIG. 7B is a side, cross-sectional view of the jaw member of FIG. 7A and a corresponding jaw member for use with the end effector assembly of FIG. 1;

FIG. 7C is a front, cross-sectional view of another embodiment of the jaw end effector assembly of FIG. 7A;

FIG. 8A is a front, cross-sectional view of another embodiment of jaw members for use with the end effector assembly of FIG. 1 showing a sealing surface of one of the jaw members spaced from the jaw member;

FIG. 8B is a front, cross-sectional view of the jaw members of FIG. 8A showing the sealing surface of one of the jaw members positioned closer to the jaw member;

FIG. 9 is a perspective view of a knife assembly in accordance with the present disclosure;

FIG. 10 is a side, cross-sectional view of the end effector assembly of the forceps of FIG. 1;

FIG. 11 is a front, cross-sectional view of another embodiment of jaw members for use with the end effector assembly of FIG. 1; and

FIG. 12 is a front, cross-sectional view of still another embodiment of jaw members for use with the end effector assembly of FIG. 1.

DETAILED DESCRIPTION

Embodiments of the presently disclosed surgical instrument are described in detail with reference to the drawing

4

figures wherein like reference numerals identify similar or identical elements. As used herein, the term “distal” refers to the portion that is being described which is further from a user, while the term “proximal” refers to the portion that is being described which is closer to a user.

Turning now to FIG. 1, a forceps 10 is provided including a housing 20, a handle assembly 30, an end effector rotating assembly 80, a trigger assembly 70 and an end effector assembly 100. Forceps 10 further includes a shaft 12 having a distal end 14 configured to mechanically engage end effector assembly 100 and a proximal end 16 that mechanically engages housing 20. Forceps 10 also includes electrosurgical cable 310 that connects forceps 10 to a generator (not shown) or other suitable power source. Cable 310 has sufficient length to extend through shaft 12 in order to provide electrical energy to at least one of jaw members 110 and 120 of end effector assembly 100. Although shown as an endoscopic surgical instrument, forceps 10 may also be configured as an open, hemostat-style surgical instrument.

With continued reference to FIG. 1, handle assembly 30 includes fixed handle 50 and a moveable handle 40. Fixed handle 50 is integrally associated with housing 20 and handle 40 is moveable relative to fixed handle 50. End effector rotating assembly 80 is rotatable in either direction about a longitudinal axis “A-A” to rotate end effector 100 about longitudinal axis “A-A.” The housing 20 houses the internal working components of the forceps 10.

Turning now to FIG. 2, end effector assembly 100 is shown attached at a distal end 14 of shaft 12 and includes a pair of opposing jaw members 110 and 120. Each of jaw members 110 and 120 includes an electrically conductive tissue sealing surface 112 and 122, respectively, that is dimensioned to oppose the other as shown in FIG. 2. End effector assembly 100 is designed as a unilateral assembly, i.e., jaw member 120 is fixed relative to the shaft 12 and jaw member 110 is moveable about a pivot 103 relative to jaw member 120. However, either, or both jaw members 110, 120 may be moveable with respect to the other. In some embodiments, as will be described in greater detail hereinbelow, a knife assembly 140 (FIG. 9) is disposed within shaft 12 and a knife channel 115 is defined within one or both jaw members 110, 120 to permit reciprocation of a knife blade 146 (FIGS. 9 and 10) therethrough.

Referring back to FIG. 1, moveable handle 40 of handle assembly 30 is ultimately connected to a drive assembly (not shown) that, together, mechanically cooperate to impart movement of jaw members 110 and 120 between an open position, a first approximated position, and a second approximated position to grasp, seal, and divide, tissue disposed between sealing surfaces 112 and 122 (FIG. 2). As shown in FIG. 1, moveable handle 40 is initially spaced-apart from fixed handle 50 and, correspondingly, jaw members 110, 120 are in the open, or spaced-apart position. Moveable handle 40 is depressible from the initial position to an intermediate position “P₁”, corresponding to the first approximated position of jaw members 110, 120, and, further, to a depressed position “P₂”, corresponding to the second approximated position of jaw members 110, 120.

When moveable handle 40 is moved to the intermediate position “P₁”, e.g., when jaw members 110, 120 are moved to the first approximated position, a specific sealing pressure is applied to tissue disposed therebetween. When moveable handle 40 is moved to the depressed position “P₂”, e.g., when jaw members 110, 120 are moved to the second approximated position, a specific cutting pressure is applied to tissue disposed therebetween. Accordingly, handle assembly 30 may be configured as a two-step mechanism, e.g., moveable

5

handle **40** may be configured to first move to the intermediate position “P₁” and then, upon the application of additional force, move from the intermediate position “P₁” to the depressed position “P₂”, or, alternatively, may be configured as a continuous, single stroke mechanism, e.g., moveable handle **40** is moved from the initial position through the intermediate position “P₁” for sealing tissue and to the depressed position “P₂” for cutting tissue. Other configurations of handle assembly **30** are also contemplated, so long as handle assembly **30** is configured to move jaw member **110**, **120** at least between the open position, the first approximated position, and the second approximated position.

Various embodiments of end effector assemblies configured for use with surgical forceps **10** will now be described in detail with reference to FIGS. 3-12. More particularly, each pair of jaw members is configured for movement between a spaced-apart position, a first approximated position, and a second approximated position. When moveable handle **40** is moved to the intermediate position “P₁” (FIG. 1), corresponding to the first approximated position, a sealing pressure is applied to tissue disposed between the jaw members. Electrosurgical energy may be communicated to the electrically conductive sealing surfaces of the respective jaw members, e.g., by actuation of trigger **70** (FIG. 1), to seal tissue disposed therebetween when the jaw members are disposed in the first approximated position. When moveable handle **40** is moved to the depressed position “P₂” (FIG. 1), corresponding to the second approximated position, a cutting pressure is applied to tissue disposed between the jaw members. Each pair of jaw members according to the various embodiments described below is configured to perforate, partially cut, and/or completely divide tissue disposed between the jaw members when the jaw members are moved to the second approximated position. As mentioned above, in some embodiments, e.g., where tissue is not fully divided, a knife blade **146** (FIG. 9) may be advanced through the jaw members to divide the perforated or partially cut tissue.

Referring now to FIG. 3, an end effector assembly **200** configured for use with surgical forceps **10** includes first and second jaw members **210** and **220**, respectively, disposed in opposing relation relative to one another and including opposed electrically conductive sealing surfaces **212**, **222**, respectively. Sealing surfaces **212**, **222** of jaw members **210**, **220**, respectively, define complementary “stepped” cross-sectional profiles, as shown in FIG. 3. More specifically, each sealing surface **212**, **222** includes a proximal portion **214**, **224** and a distal portion **216**, **226** interconnected by a “stepped” portion **218**, **228**, respectively, defined longitudinally therealong. The stepped portions **218**, **228** include steps **219**, **229**, respectively, that offset the proximal portions **214**, **224** and distal portions **216**, **226** of the respective sealing surfaces **212**, **222** from one another. Thus, as shown in FIG. 3, proximal portion **214** of sealing surface **212** of jaw member **210** is offset below distal portion **216** of sealing surface **212** of jaw member **210** and, similarly, proximal portion **224** of sealing surface **222** of jaw member **220** is offset below distal portion **226** of sealing surface **222** of jaw member **220**.

The complementary stepped portions **218**, **228** of sealing surfaces **212**, **222** of jaw members **210**, **220**, respectively, may be positioned more proximally or more distally along the respective jaw members **210**, **220** than as shown in FIG. 3. Alternatively, the complementary stepped portions **218**, **228** may be defined laterally across sealing surfaces **212**, **222** of jaw members **210**, **220** to define a “stepped” front cross-section (see FIG. 11, for example). Further, steps **219**, **229** may be angled distally or proximally with respect to sealing surfaces **212**, **222** from the substantially perpendicular posi-

6

tion shown in FIG. 3. Multiple stepped portions and/or multiple steps positioned along sealing surfaces **212**, **222** are also contemplated.

In use, as mentioned above, moveable handle **40** is moved from the initial position to the intermediate position “P₁” (FIG. 1) and, accordingly, jaw members **210**, **220** are moved from the spaced-apart position to the first approximated position. In the first approximated position, sealing surfaces **212**, **222** grasp tissue disposed therebetween according to a specific sealing pressure. Electrosurgical energy is conducted through sealing surfaces **212**, **222** and through tissue to effect a tissue seal.

Upon further depression of moveable handle **40**, moveable handle **40** reaches the depressed position “P₂” (FIG. 1) wherein jaw members **210**, **220** are moved to the second approximated position to apply a specific cutting pressure to the sealed tissue disposed between sealing surfaces **212**, **222** of jaw members **210**, **220**, respectively. In the second approximated position, the pressure applied by jaw members **210**, **220** to tissue, e.g., the cutting pressure, is sufficiently great at stepped portions **218**, **228**, such that the combination of the tension on tissue and the approximation of steps **219**, **229** of complementary stepped portions **218**, **228** of sealing surfaces **212**, **222**, respectively, severs, or divides tissue disposed therebetween.

With reference now to FIG. 4, end effector assembly **300** is shown configured for use with surgical forceps **10**. End effector assembly **300** includes a pair of jaw members **310**, **320**, each including an opposed electrically conductive sealing surface **312**, **322**. Jaw member **310** includes a protrusion, e.g., an elongated flange **314**, extending longitudinally along and protruding from sealing surface **312**. Elongated flange **314** may define a rectangular front cross-section, as shown in FIG. 4, or may define another cross-section, e.g., circular, square, diamond, etc. Jaw member **320** includes an elongated recess **324** defined within and extending longitudinally along sealing surface **322**. Elongated recess **324** is shaped complementary to elongated flange **314**, i.e., recess **324** defines a rectangular front cross-section, and may define a substantially equal or slightly larger diameter than elongated flange **314** such that, upon movement of jaw members **310**, **320** to the approximated positions, elongated flange **314** is at least partially disposed within elongated recess **324**.

In use, moveable handle **40** is moved to the intermediate position “P₁” (FIG. 1) to thereby move jaw members **310**, **320** to the first approximated position wherein sealing surfaces **312**, **322** impart a specific sealing pressure to tissue grasped therebetween. Electrosurgical energy may then be conducted through sealing surfaces **312**, **322** and through tissue to effect a tissue seal.

As in the previous embodiment, depressing moveable handle **40** to the depressed position “P₂” (FIG. 1) moves jaw members **310**, **320** to the second approximated position such that a specific cutting pressure is applied to the sealed tissue disposed between sealing surfaces **312** and **322**. In the second approximated position, the cutting pressure applied by jaw members **310**, **320** to tissue is sufficiently great such that, the tension on tissue and the engagement of protrusion **314** within recessed portion **324**, severs, or divides tissue disposed therebetween.

Referring now to FIG. 5, end effector assembly **400** is configured for use with surgical forceps **10** and includes a pair of jaw members **410**, **420**, each including an opposed electrically conductive sealing surface **412**, **422**. Jaw member **410** includes an elongated half-cylindrical flange **414** extending longitudinally along and protruding from sealing surface **412**. Jaw member **420** includes an elongated half-cylindrical cut-

out, or recess **424** defined within and extending longitudinally along sealing surface **422**. Recess **424** is shaped substantially complementary to flange **414** and may define a substantially equal, or slightly smaller radius as compared to flange **414** such that, upon movement of jaw members **410**, **420** to the second approximated position, flange **414** engages recess **424** and, optionally, urges recess **424** to expand in the direction of arrows "R."

In use, end effector assembly **400** operates similarly to end effector assembly **300** in that moveable handle **40** is moved to the intermediate position "P₁" (FIG. 1) to impart a specific sealing pressure to tissue such that electrosurgical energy may then be applied to seal tissue disposed between jaw member **410** and **420**. As in the previous embodiment, moveable handle **40** is then moved to the depressed position "P₂" (FIG. 1) to move jaw members **410**, **420** to the second approximated position, thereby applying a specific cutting pressure to the sealed tissue disposed between sealing surfaces **412** and **422** and, more particularly, to tissue disposed between cylindrical portion **414** and cylindrical recess **424**. In the second approximated position, cylindrical protrusion **414** of jaw member **410** engages cylindrical recess **424** of jaw member **420** and urges cylindrical recess **424** to expand in the direction of arrows "R." The tension on tissue disposed between cylindrical protrusion **414** and cylindrical recess **424** and the engagement of protrusion **414** within recess **424** when jaw member **410**, **420** are in the second approximated position causes tissue disposed therebetween to be cut, or divided.

Turning now to FIGS. 6A-6B, end effector assembly **500** is configured for use with surgical forceps **10** and includes first and second jaw members **510** and **520**, respectively. Jaw member **510**, as shown in FIG. 6A, includes a plurality of protrusions **514**, **516** extending therefrom. More specifically, protrusions **514** form a first column extending longitudinally along sealing surface **512** and protrusions **516** form a second column extending longitudinally along sealing surface **512**. The configuration of protrusions **514**, **516** shown in FIG. 6A is an example of one configuration; however, protrusions **514**, **516** may define greater or fewer columns, or may be arranged in different configurations. Further, the protrusions **514**, **516** need not be triangular, as shown in FIGS. 6A-6B, but may, for example, define a square, diamond, or other shape configuration.

As shown in FIG. 6B, jaw member **520** includes a column of triangular recesses, or detents **524** defined within sealing surface **522** and extending longitudinally therealong. Triangular detents **524** are shaped and positioned complementarily to protrusions **514**. A second column of detents (not shown) complements column of protrusions **516** such that, as jaw members **510**, **520** are moved to the approximated positions, protrusions **514**, **516** engage complementary shaped detents **524**, (not shown). As with protrusions **514**, **516**, detents **524** need not be arranged in the configuration shown in FIG. 6A, so long as detents **524** are positioned and configured complementarily to protrusions **514**, **516**. Further, the configuration of protrusions **514**, **516** and detents **524** may be reversed, e.g., protrusions **514**, **516** may be positioned along sealing surface **522** of jaw member **520** and detents **524** may be defined within sealing surface **512** of jaw member **510**, or jaw members **510** and **520** may include complementary sealing surfaces **512**, **522**, respectively, including complementary protrusions **514**, **516** and detents **524** on each of jaw members **510**, **520**.

In use, as in the previous embodiments, moveable handle **40** is moved to the intermediate position "P₁" (FIG. 1) for sealing tissue. In the intermediate position "P₁" (FIG. 1) a specific sealing pressure is imparted to tissue grasped

between jaw member **510**, **520** and electrosurgical energy is conducted through sealing surfaces **512**, **522** and through tissue to effect a tissue seal.

Jaw members **510**, **520** are then moved to the second approximated position by depressing moveable handle **40** to the depressed position "P₂" (FIG. 1). In this position, a specific cutting pressure is applied to the sealed tissue disposed between sealing surfaces **512** and **522**. With the application of the cutting pressure to tissue disposed between jaw members **510**, **520**, the engagement of protrusions **514**, **516** within complementary recesses **524**, (not shown) acts to perforate tissue disposed between protrusions **514**, **516** and recesses **524**, (not shown). With columns of perforations in tissue, tissue may more easily be torn, or divided. Additionally, a knife channel (not shown) may be defined within one (or both) sealing surfaces **512**, **522** such that, a knife blade, e.g., knife blade **146** (FIG. 9) of knife assembly **140** (FIG. 9), may be advanced through the perforated tissue to more easily sever tissue. In such an embodiment, the incidents of blade splay would be reduced since blade **146** (FIG. 9) would more easily cut through the perforated (weakened) tissue as blade **146** (FIG. 9) is advanced distally through the knife channel **115** (FIG. 2).

With reference now to FIGS. 7A-7B, an end effector assembly **600** configured for use with surgical forceps **10** includes first and second jaw members **610**, **620**, respectively. Each jaw member includes an opposed sealing surface **612**, **622**, respectively. One, or both jaw members, e.g., jaw member **620** (FIG. 7A), may include a ceramic bar **630** extending longitudinally therealong. Ceramic bar **630** may be centered with respect to jaw member **620** (as shown) or may be positioned off-center. Upon movement of jaw members **610**, **620** to the approximated positions, as shown in FIG. 7B, ceramic bar **630** of jaw member **620** approaches a mating relationship with sealing surface **612** (or the corresponding ceramic bar) of jaw member **610**. Alternatively, as shown in FIG. 7C, ceramic bar **630**, which extends along jaw member **620**, may define a circular cross-section and may be configured to cooperate with a recess defined within jaw member **620** upon movement of jaw members **610**, **620** to the approximated positions.

In use, as mentioned above, moveable handle **40** is moved from the initial position to the intermediate position "P₁" (FIG. 1) and, accordingly, jaw members **610**, **620** are moved to the first approximated position. With the jaw members applying a specific sealing pressure, electrosurgical energy is conducted through sealing surfaces **612**, **622** and through tissue to effect a tissue seal. When jaw members **610**, **620** are in the first approximated position, ceramic bar **630** may function to define a gap distance between sealing surfaces **612**, **622**. Moving jaw members **610**, **620** to the second approximated position (corresponding to position "P₂" (FIG. 1)) applies a specific cutting pressure to tissue disposed between ceramic bar **630** of jaw member **620** and sealing surface **612** of jaw member **610**. More particularly, in the second approximated position, ceramic bar **630** is urged through tissue to divide tissue disposed therebetween.

Turning now to FIGS. 8A-8B, an end effector assembly **700** configured for use with surgical forceps **10** includes first and second jaw members **710** and **720**, respectively. Jaw member **710** includes an electrically conductive sealing plate **712**, and more particularly, electrically conductive sealing plate halves **712a** and **712b** that are moveably coupled to jaw member **710** via springs, or actuators **714a**, **714b** (collectively springs **714**). Springs, or actuators **714** may include cantilever beams, coil springs, shape memory materials, hydraulic members, cam members, elastomers, or the like. Springs **714**

9

bias sealing plate 712 toward a spaced-apart position with respect to jaw member 710 and are compressible such that sealing plate 712 is moveable to a closer position with respect to jaw member 710. Jaw member 710 further includes a blade 740 fixedly engaged to jaw member 710 and extending longitudinally at least partially therealong. Initially, as shown in FIG. 8A, when sealing plate 712 is in the spaced-apart position with respect to jaw member 710, blade 740 is disposed within jaw member 710, i.e., blade 740 is not exposed. Upon compression of springs 714 (or retraction of actuators 714), as shown in FIG. 8B, sealing plate halves 712a, 712b are moved to the closer position with respect to jaw member 710 such that blade 740 extends beyond sealing plate 712, i.e., blade 740 is exposed. Springs 714 may be configured to compress upon application of the cutting pressure to tissue disposed between jaw members 710, 720, e.g., upon movement of jaw members 710, 720 to the second approximated position, such that when jaw members are moved to the second approximated position, blade 740 is advanced through tissue disposed between jaw members 710 and 720. Further, sealing plate 712 need not be moveably coupled to jaw member 710 by springs 714, but may be coupled thereto by any suitable spring-like, or actuation mechanism. Additionally, the gap distances “a” between blade sealing plate halves 712a, 712b and blade 740 may be varied to achieve a particular cutting characteristic or characteristics.

Continuing with reference to FIGS. 8A-8B, jaw member 720 includes an electrically conductive sealing plate 722 fixedly engaged thereto and opposed to sealing plate 712. Sealing plate 722 includes first and second sealing plate halves 722a, 722b, respectively. A recess 750 is defined within jaw member 720 between first and second sealing plate halves 722a and 722b, respectively. Recess 750 is configured to permit blade 740 to extend into jaw member 720 upon movement of sealing plate 712 to the closer position with respect to jaw member 710, as shown in FIG. 8B. Alternatively, sealing plate halves 722a, 722b may be moveably coupled to jaw member 720 and may include a fixed blade (not shown) disposed therein. In such an embodiment, sealing plate halves 712a and 712b are fixedly engaged to jaw member 710 on either side of a recess (not shown). In other words, the configuration of jaw members 710 and 720 may be reversed to achieve the same result as described above.

In use, moveable handle 40 is moved from the initial position to the intermediate position “P₁” (FIG. 1) and, accordingly, jaw members 710, 720 are moved from the spaced-apart position to the first approximated position to grasp tissue therebetween. In the first approximated position, sealing plates 712, 722 grasp tissue according to a specific sealing pressure. Springs 714a, 714b are configured with a sufficient stiffness such that, when the sealing pressure is applied, i.e., when jaw members 710, 720 are in the first approximated position, sealing plate 712 remains spaced from jaw member 710, i.e., springs 714 are not compressed. Accordingly, in the first approximated position, fixed blade 740 is not exposed (See FIG. 8A). Electrosurgical energy may be conducted through sealing plates 712, 722 and through tissue to effect a tissue seal when jaw members 710, 720 are in this first approximated position.

Upon further depression of moveable handle 40 to the depressed position “P₂” (FIG. 1), jaw members 710, 720 are moved to the second approximated position wherein a specific cutting pressure is applied to the sealed tissue disposed between sealing plates 712 and 722. The cutting pressure is sufficiently great to compress springs 714a, 714b such that sealing plate 712 is moved to the closer position with respect to jaw member 710. As sealing plate 712 is moved toward jaw

10

member 710, fixed blade 740 is exposed, eventually advancing through tissue disposed between sealing plates 712, 722 and into recess 750, as shown in FIG. 8B. As fixed blade 740 is advanced through tissue, fixed blade 740 cuts, or divides tissue.

With reference now to FIGS. 9 and 10, knife assembly 140 is shown including a knife rod 142, a knife bar 144, and a knife blade 146 disposed at a distal end 145 of knife bar 144. A proximal end 147 of knife bar 144 is fixedly engaged to knife rod 142, e.g., via a pin-aperture engagement. Knife assembly 140 is positioned within shaft 12, as best shown in FIG. 10, and is selectively translatable to advance knife blade 146 distally into knife channel(s) 115 (see FIG. 2) defined within either or both jaw members 110, 120 to cut tissue disposed between the jaw members 110, 120. Knife assembly 140, including knife channel 115 may be provided for use with the embodiments described below, or with any of the embodiments above, to facilitate cutting of tissue disposed between jaw members 110, 120 when jaw members 110, 120 are disposed in the second approximated position.

Referring now to FIG. 11 in conjunction with FIGS. 9 and 10, end effector assembly 800 is configured for use with surgical forceps 10 and includes first and second jaw members 810, 820 each having an opposed electrically conductive sealing surface 812, 822, respectively. More specifically, each jaw member 810, 820 includes a pair of sealing surface portions, or halves 816, 818 and 826, 828, respectively, separated by knife channel halves 815a, 815b, respectively. Upon movement of jaw members 810, 820 to the second approximated position, knife channel halves 815a, 815b align to form a complete knife channel configured to permit reciprocation of a knife blade 146 (FIG. 10) therethrough.

As shown in FIG. 11, sealing surface portions, or halves 816 and 818 are offset from one another and similarly, sealing surface halves 826 and 828 are offset from one another. More particularly, sealing surface halves 816 and 826 are offset above sealing surface halves 818 and 828, respectively, such that each jaw member 810, 820 defines a complementary “stepped” front cross-section, with knife channels 815a, 815b, respectively, therebetween.

In use, when jaw members 810, 820 are moved to the first approximated position, sealing surfaces 812, 822 grasp tissue disposed therebetween according to a specific sealing pressure. More particularly, sealing surface halves 816 and 826 grasp tissue on one side of knife channels 815a, 815b and sealing surface halves 818 and 828 grasp tissue on the other side of knife channels 815a, 815b. Electrosurgical energy is conducted through the sealing surfaces 812, 822 and through tissue to effect a tissue seal on both sides of knife channels 815a, 815b.

Moveable handle 40 is then moved to the depressed position “P₂” (FIG. 1) to move jaw members 810, 820 to the second approximated position. In the second approximated position, the pressure, e.g., the cutting pressure, applied to tissue disposed between sealing surface halves 816, 826 and 818, 828 and the offset configuration of jaw members 810, 820 tensions tissue positioned between knife channels 815a, 815b. This tension itself may tear tissue disposed between knife channels 815a and 815b, and/or may provide weakened tissue such that a user may advance knife blade 146 of knife assembly 140 from the shaft 12 and into the knife channels 815a, 815b to more easily sever the weakened tissue.

Turning now to FIG. 12 in conjunction with FIGS. 9 and 10, end effector assembly 900 is configured for use with surgical forceps 10 and includes first and second jaw members 910 and 920. Jaw member 910 includes an electrically conductive sealing surface 912 that opposes an electrically

11

conductive sealing surface **922** disposed on jaw member **920**. Jaw member **910** further includes a cylindrical-shaped recess **914** defined therein and extending therealong. Jaw member **920** includes a complementary cylindrical-shaped portion **924** protruding therefrom and extending therealong. A knife channel **915** is defined within cylindrical-shaped protrusion **924** such that, upon movement of jaw members **910**, **920** to the second approximated position, knife blade **146** (FIG. **10**) may be advanced through knife channel **915** to cut tissue disposed between jaw members **910** and **920**. As in any of the previous embodiments, the configuration of the jaw members **910**, **920** may be reversed.

In use, end effector assembly **900** operates similarly to end effector assembly **800**. Thus, jaw members **910**, **920** are initially moved to the first approximated position for sealing tissue disposed between sealing surfaces **912**, **922**. Next, jaw members **910**, **920** are moved to the second approximated position wherein the cutting pressure and the complementary cylindrical-shaped sections **914**, **924** tension tissue disposed between cylindrical-shaped protrusion **924** and cylindrical-shaped recess **914**. As in the previous embodiment, this tensioning itself may tear tissue therebetween and/or may provide weakened tissue such that a user may advance knife blade **146** of knife assembly **140** from shaft **12** and into the knife channel **915** to more easily sever the weakened tissue.

From the foregoing and with reference to the various figure drawings, those skilled in the art will appreciate that certain modifications can also be made to the present disclosure without departing from the scope of the same. While several embodiments of the disclosure have been shown in the drawings, it is not intended that the disclosure be limited thereto, as it is intended that the disclosure be as broad in scope as the art will allow and that the specification be read likewise. Therefore, the above description should not be construed as limiting, but merely as exemplifications of particular embodiments. Those skilled in the art will envision other modifications within the scope and spirit of the claims appended hereto.

What is claimed:

1. An end effector assembly for a surgical instrument, comprising:

first and second jaw members disposed in opposing relation relative to one another, at least one of the first and second jaw members moveable relative to the other between a spaced-apart position, a first approximated position, and a second approximated position, the first jaw member including:

a jaw body;

a blade engaged to the jaw body; and

a pair of plate sections operably coupled to the jaw body and positioned to define an interior area between the plate sections and the jaw body, the plate sections spaced-apart from one another to define a first channel therebetween in communication with the interior area,

wherein, with the first and second jaw members disposed in the first approximated position with tissue grasped therebetween, the plate sections are disposed in an extended position relative to the jaw body such that the blade is retained within the interior area, and wherein, with the first and second jaw members disposed in the second approximated position with tissue grasped therebetween, the plate sections are disposed in a retracted position relative to the jaw body such that the blade extends from the interior area and through the first channel to cut tissue grasped between the jaw members.

12

2. The end effector assembly according to claim 1, wherein the second jaw member includes:

a jaw body; and

a plate disposed on the jaw body, wherein the plate sections of the first jaw member and the plate of the second jaw member are configured to grasp tissue therebetween in the first and second approximated positions of the first and second jaw members.

3. The end effector assembly according to claim 2, wherein the plate of the second jaw member includes a pair of plate sections spaced-apart from one another to define a second channel therebetween positioned opposite of the first channel, the second channel configured to at least partially receive the blade in the second approximated position of the first and second jaw members.

4. The end effector assembly according to claim 1, wherein the first and second jaw members are configured to apply a first pre-determined pressure to tissue grasped therebetween in the first approximated position, and wherein the first and second jaw members are configured to apply a second pre-determined pressure to tissue grasped therebetween in the second approximated position.

5. The end effector assembly according to claim 1, wherein at least one of the first and second jaw members is adapted to connect to a source of energy for conducting energy through tissue grasped between the first and second jaw members.

6. The end effector assembly according to claim 1, further including a pair of actuators coupling the plate sections of the first jaw member to the jaw body of the first jaw member.

7. The end effector assembly according to claim 6, wherein the pair of actuators are selected from the group consisting of: coil springs, cantilever beams, shape memory actuators, hydraulic actuators, cam members, and elastomers.

8. The end effector assembly according to claim 6, wherein the actuators bias the plate sections towards the extended position.

9. The end effector assembly according to claim 1, wherein the blade is integrally formed with the jaw body.

10. A forceps, comprising:

an end effector assembly including:

first and second jaw members disposed in opposing relation relative to one another, at least one of the first and second jaw members moveable relative to the other between a spaced-apart position, a first approximated position, and a second approximated position, the first jaw member including:

a jaw body;

a blade engaged to the jaw body; and

a pair of plate sections operably coupled to the jaw body and positioned to define an interior area between the plate sections and the jaw body, the plate sections spaced-apart from one another to define a first channel therebetween in communication with the interior area; and

a handle assembly including a fixed handle and a movable handle operably coupled to the end effector assembly, the movable handle movable relative to the fixed handle between a first position, a second position, and a third position for moving the first and second jaw members between the spaced-apart position, the first approximated position, and the second approximated position, wherein, with the movable handle disposed in the second position and the first and second jaw members disposed in the first approximated position with tissue grasped therebetween, the plate sections are disposed in an extended position relative to the jaw body such that the blade is retained within the interior area, and

13

wherein, with the movable handle disposed in the third position and the first and second jaw members disposed in the second approximated position with tissue grasped therebetween, the plate sections are disposed in a retracted position relative to the jaw body such that the blade extends from the interior area and through the first channel to cut tissue grasped between the jaw members.

11. The forceps according to claim **10**, wherein the second jaw member includes:

a jaw body; and

a plate disposed on the jaw body, wherein the plate sections of the first jaw member and the plate of the second jaw member are configured to grasp tissue therebetween in the first and second approximated positions of the first and second jaw members.

12. The forceps according to claim **11**, wherein the plate of the second jaw member includes a pair of plate sections spaced-apart from one another to define a second channel therebetween positioned opposite of the first channel, the second channel configured to at least partially receive the blade in the second approximated position of the first and second jaw members.

14

13. The forceps according to claim **10**, wherein the first and second jaw members are configured to apply a first pre-determined pressure to tissue grasped therebetween in the first approximated position, and wherein the first and second jaw members are configured to apply a second pre-determined pressure to tissue grasped therebetween in the second approximated position.

14. The forceps according to claim **10**, wherein at least one of the first and second jaw members is adapted to connect to a source of energy for conducting energy through tissue grasped between the first and second jaw members.

15. The forceps according to claim **10**, further including a pair of actuators coupling the plate sections of the first jaw member to the jaw body of the first jaw member.

16. The forceps according to claim **15**, wherein the pair of actuators are selected from the group consisting of: coil springs, cantilever beams, shape memory actuators, hydraulic actuators, cam members, and elastomers.

17. The forceps according to claim **15**, wherein the actuators bias the plate sections towards the extended position.

18. The forceps according to claim **10**, wherein the blade is integrally formed with the jaw body.

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